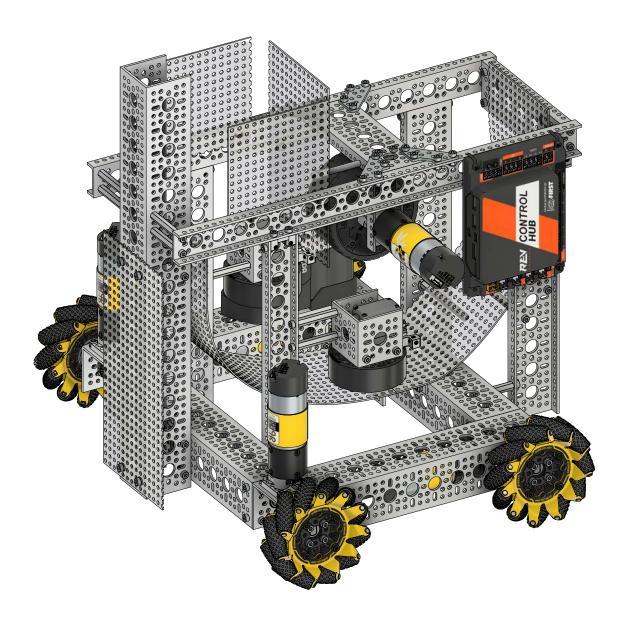
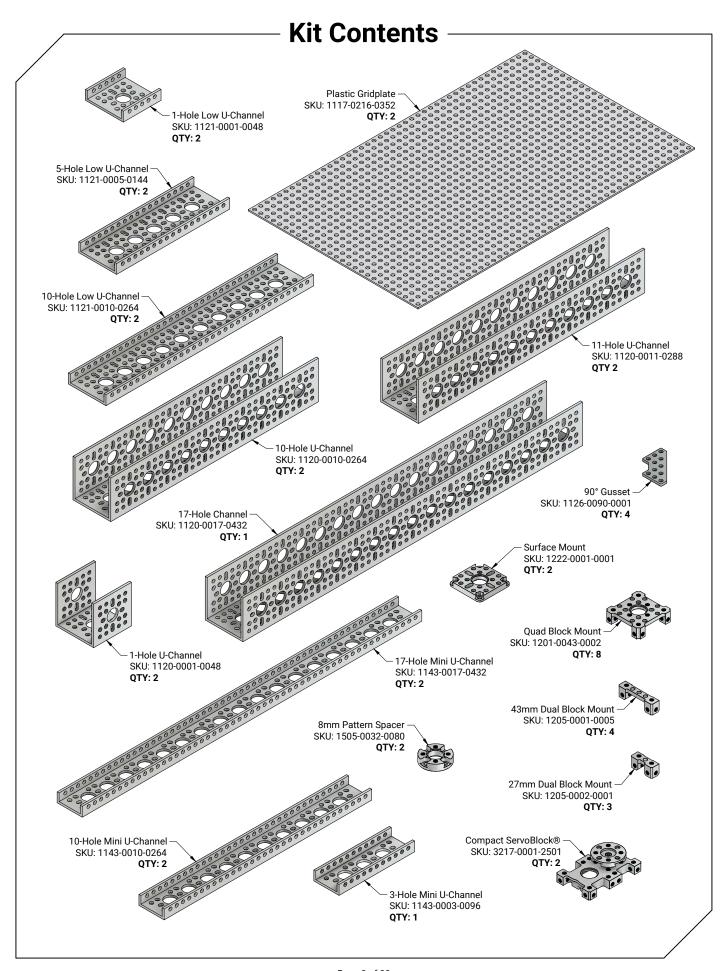


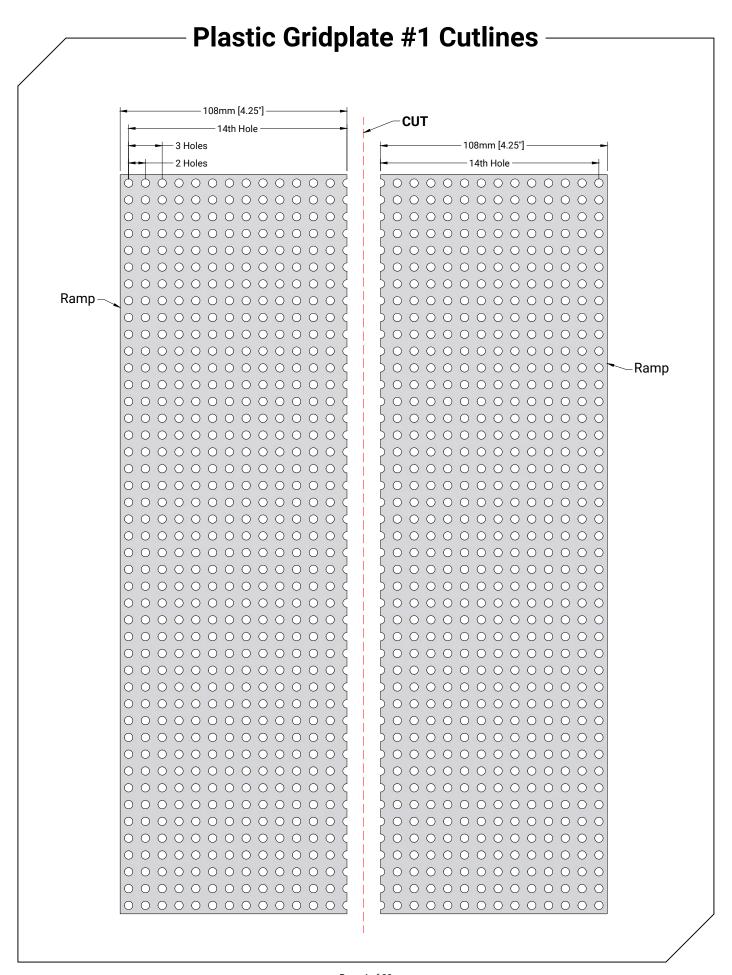
# Assembly Instructions for FTC Starter Bot with Mecanum Wheels (for DECODE™) Built from:

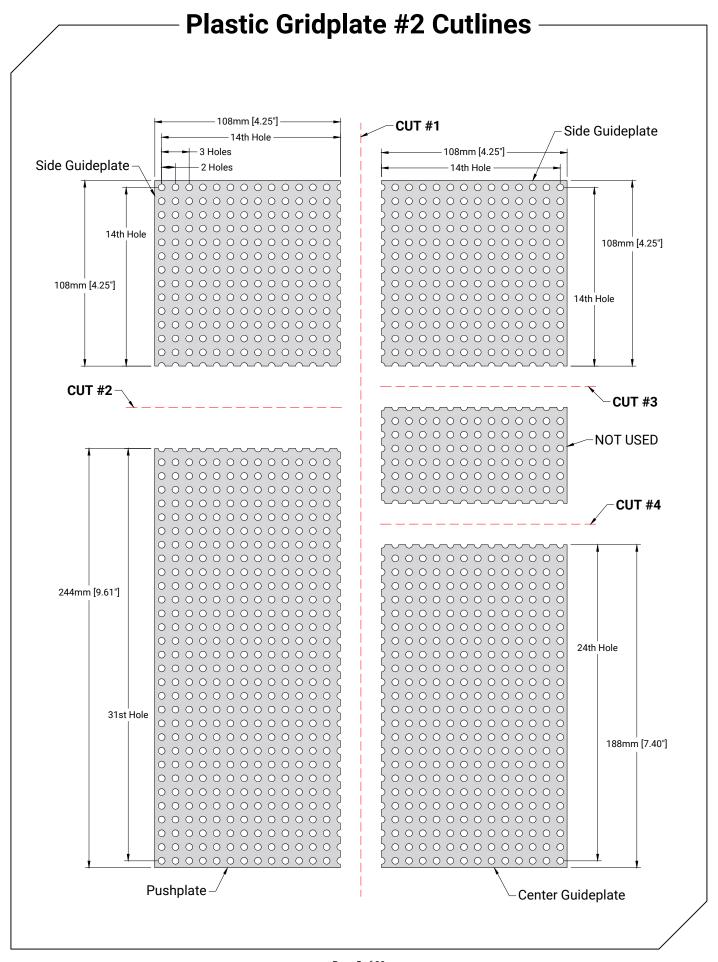
1 x FTC Stater Kit (SKU: 3200-4008-2526) 1 x Strafer® Chassis (SKU: 3209-0001-0007) 2 x Flat Pattern Mount (SKU: 1222-0001-0001)

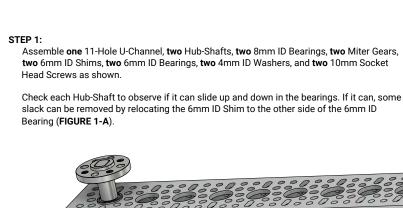


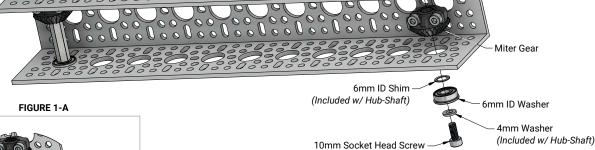


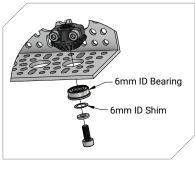
#### **Kit Contents** (Cont) Left-Slant Mecanum Wheel 19.2:1 Ratio Yellow Jacket Motor SKU: 3625-0100-0104 SKU: 5203-2402-0019 QTY: 2 8mm Socket Head Screw QTY: 5 SKU: 2800-0004-0008 QTY: 80 10mm Socket Head Screw SKU: 2800-0004-0010 QTY: 74 12mm Socket Head Screw SKU: 2800-0004-0012 OTY: 48 Gecko® Wheel SKU: 3613-0014-0072 14mm Socket Head Screw QTY: 2 SKU: 2800-0004-0014 Right-Slant Mecanum Wheel QTY: 8 SKU: 3625-0001-0104 QTY: 2 20mm Socket Head Screw Speed Servo SKU: 2800-0004-0020 SKU: 2000-0025-0003 QTY: 4 Hogback Wheel QTY: 2 SKU: 3626-0014-0096 Washer OTY: 2 SKU: 2801-0004-0008 QTY: 40 0.5mm Thick, 8mm ID Shim 80mm Length, 8mm REX™ Shaft SKU: 2807-0811-0500 **Hub-Shaft** SKU: 2106-4008-0800 OTY: 4 SKU: 2110-0608-0002 QTY: 4 QTY: 4 Locknut SKU: 2812-0004-0007 QTY: 44 17T, 1:1 Coupler 43mm Length, 6mm Round Standoff SKU: 5105-0107-0019 SKU: 1501-0006-0430 QTY: 1 9mm Length, 8mm ID Spacer 11T, 1:1 Coupler 24mm Length, 8mm REX™ Standoff SKU: 1522-0010-0090 SKU: 1516-4008-0240 SKU: 5105-0209-0019 QTY: 2 QTY: 1 12mm Length, 8mm ID Spacer 8mm REX™ Hyper Hub 43mm Length, 8mm REX™ Standoff SKU: 1522-0010-0120 SKU: 1310-0016-4008 SKU: 1516-4008-0430 QTY: 2 QTY: 1 QTY: 4 6mm ID Bearing 48mm Length, 8mm REX™ Standoff Miter Gear SKU: 1611-0514-0006 SKU: 1516-4008-0480 SKU: 2320-4008-0024 QTY: 4 QTY: 4 QTY: 8 7mm Wrench 8mm ID Bearing SKU: 4202-0070-1070 SKU: 1611-0514-0008 Zip-Tie SKU: 2909-0101-0100 QTY: 1 QTY: 11 2.5mm Hex-Plus L-Key **Battery Mount** SKU: 5027103001 SKU: 1209-0001-0001 QTY: 1 3mm Hex-Plus L-Key SKU: 5027104001 **REV Control Hub** SKU: REV-31-1595 QTY: 1 (Not Included) **Battery Strap** 12V Battery SKU: 1209-0001-0001 SKU: 3100-0012-0020 QTY: 1 (Included w/ Battery Mount) QTY: 1









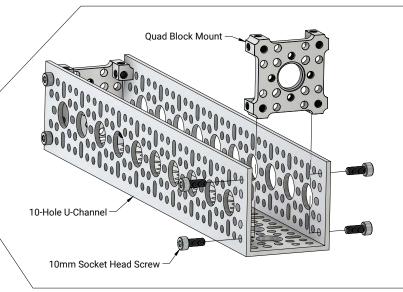


#### STEP 2:

Use **eight** 10mm Socket Head Screws to attach **two** Quad Block Mounts to **one** 10-Hole U-Channel as shown.

# STEP 3:

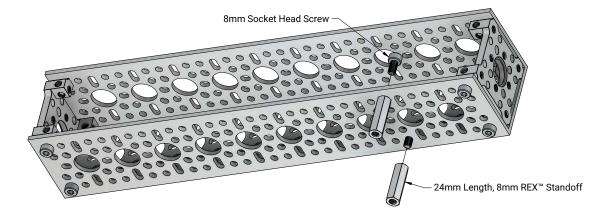
Use **two** 8mm Socket Head Screws to attach **two** 24mm Length, 8mm REX™ Standoffs as shown.

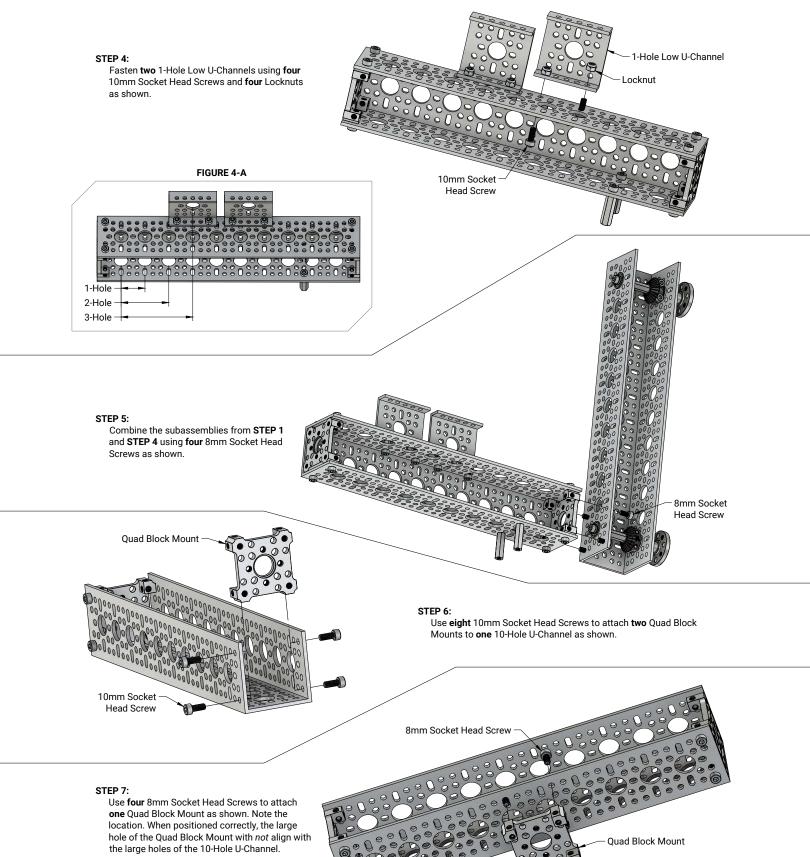


(Included w/ Hub-Shaft)

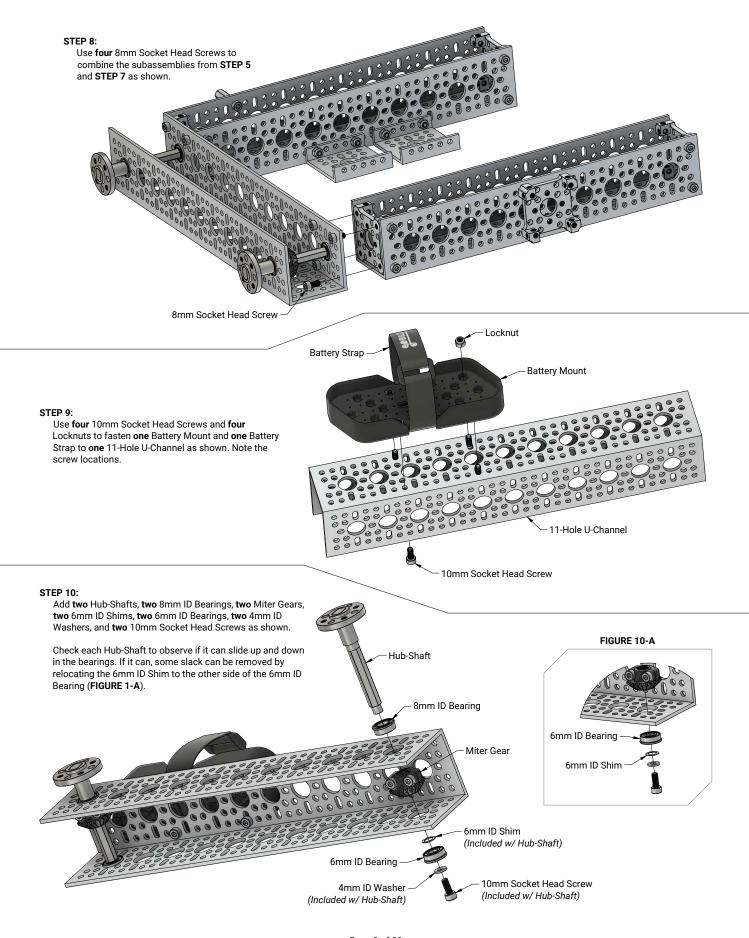
Hub-Shaft

8mm ID Bearing

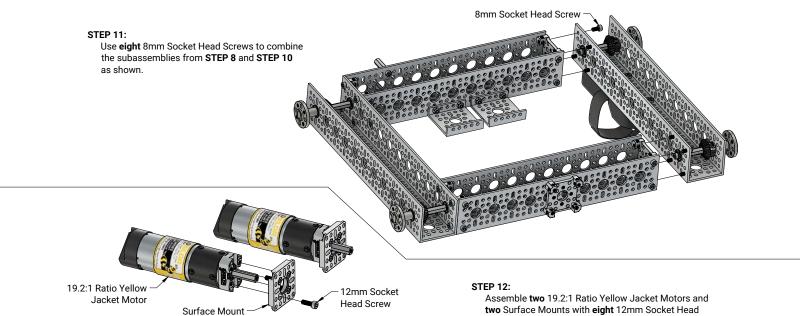




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#### **STEP 13:**

Miter Gear

10mm Socket Head Screw

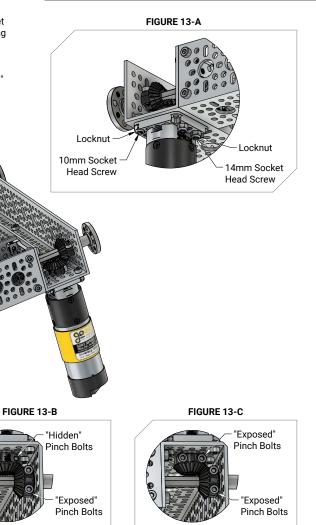
Combine the subassemblies from STEP 12 and STEP 13 using four 10mm Socket Head Screws, four 14mm Socket Head Screws, and eight Locknuts while installing two 12mm Length, 8mm ID Spacers and two Miter Gears as shown. Note the locations of the different screws (FIGURE 13-A).

Take note of the gear mesh. It is recommended to ensure the gears are "in-phase" (FIGURE 12-B), as opposed to "out-of-phase" (FIGURE 12-C). The easiest way to tell is to make sure the pinch-bolts on one of the Miter Gears is "exposed", while the others are "hidden".

14mm Socket Head Screw

12mm Length,

8mm ID Spacer

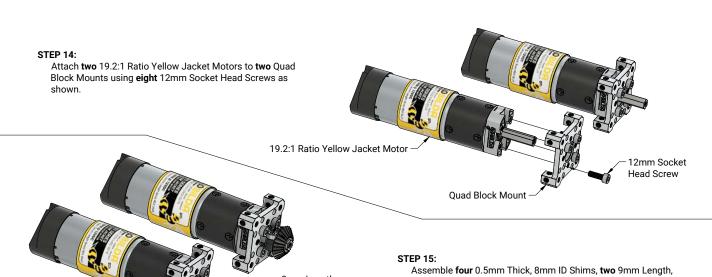


"Out-Of-Phase" Miter Gears

Screws as shown.

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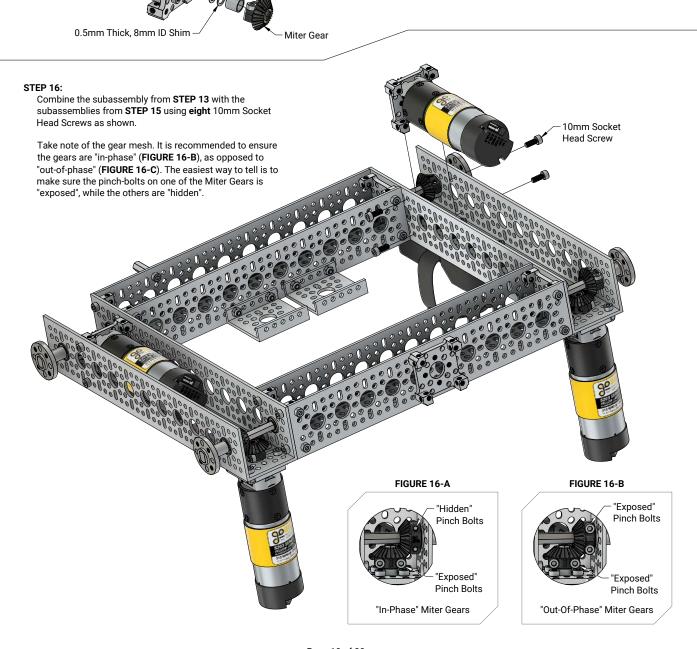
"In-Phase" Miter Gears



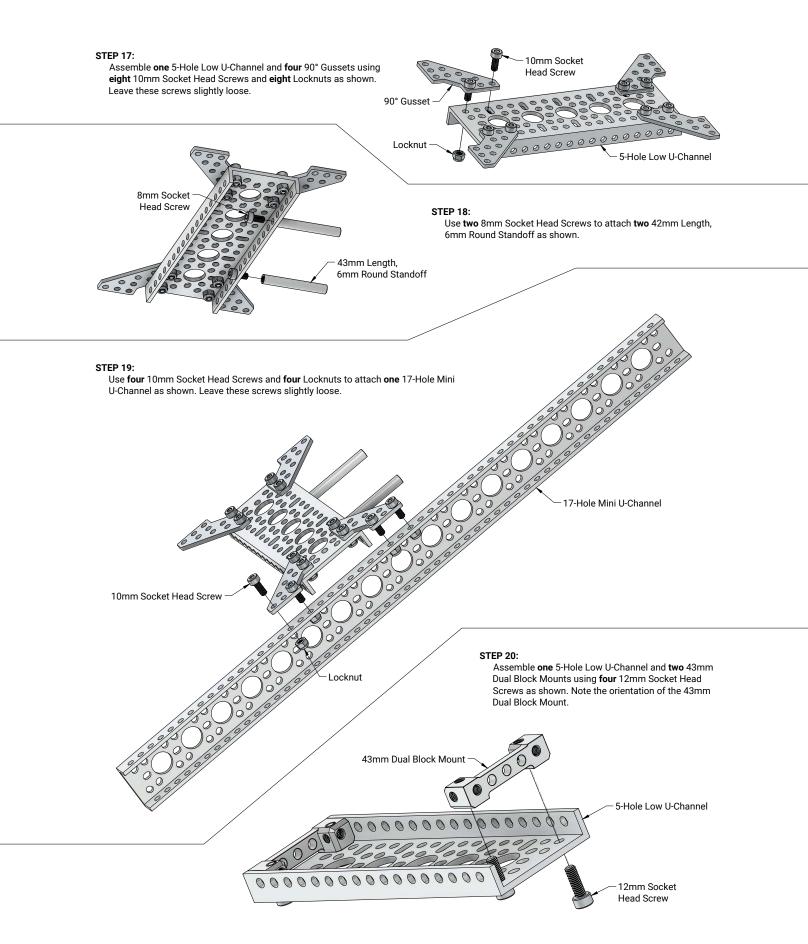
8mm ID Spacers, and two Miter Gears as shown.

9mm Length,

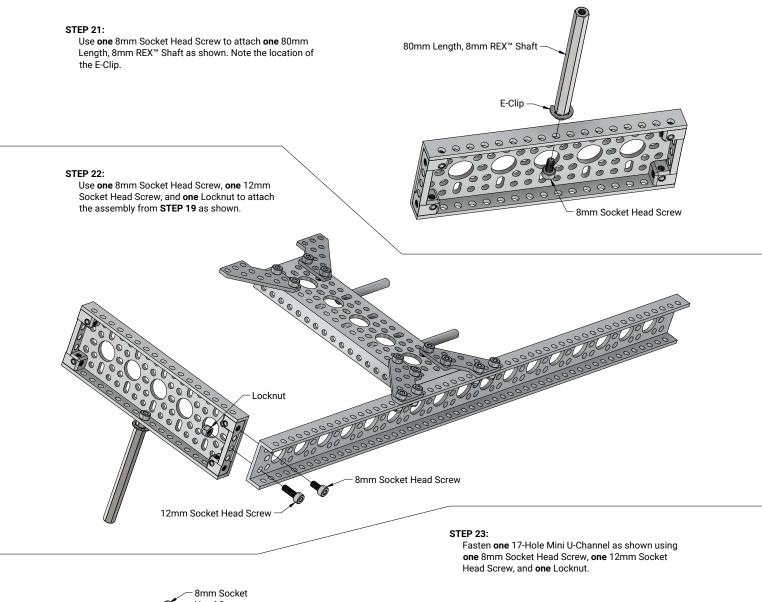
8mm ID Spacer

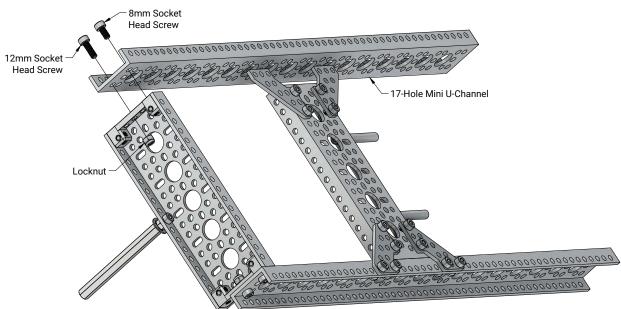


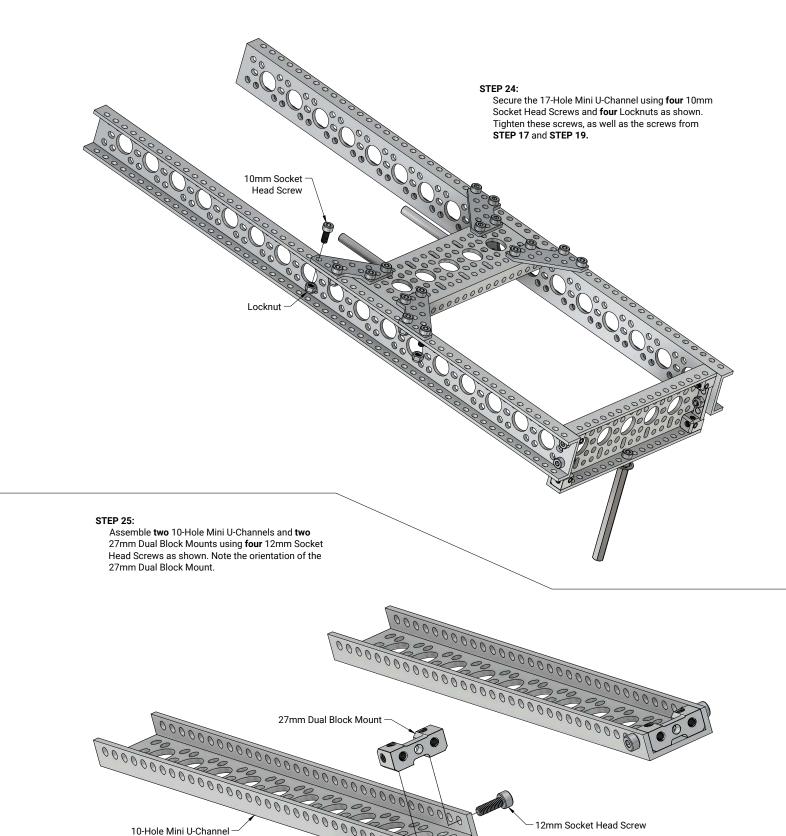
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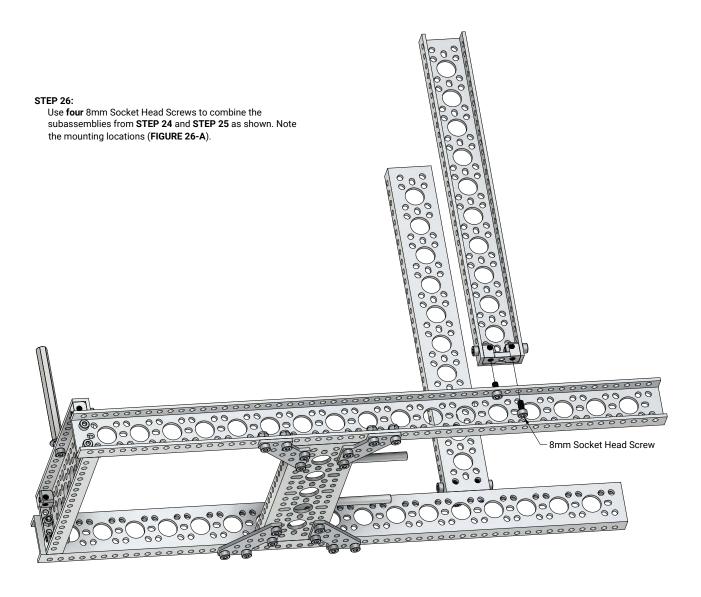


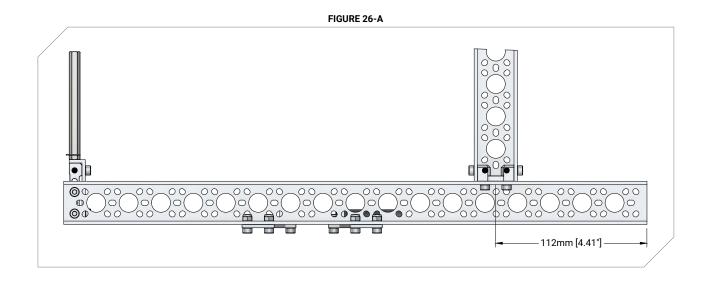
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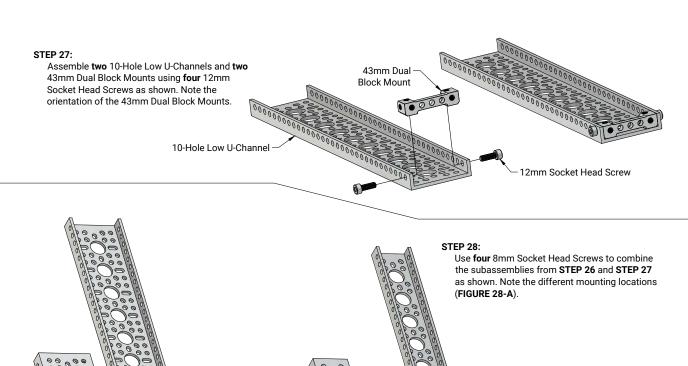


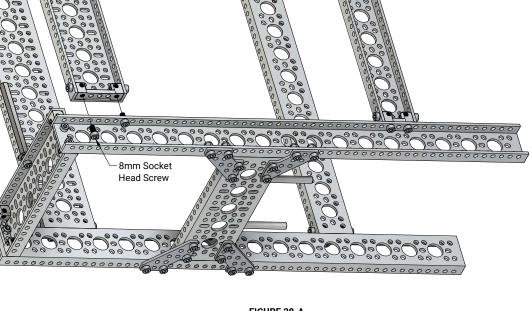


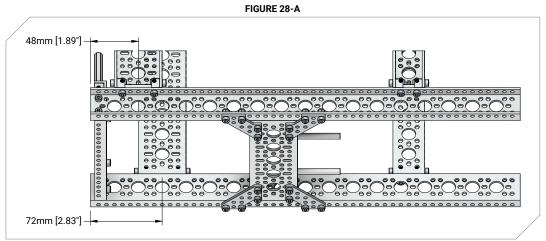


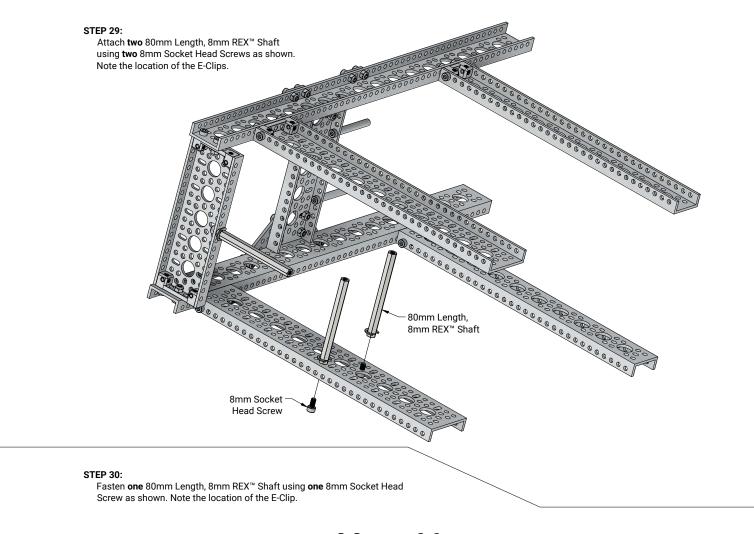


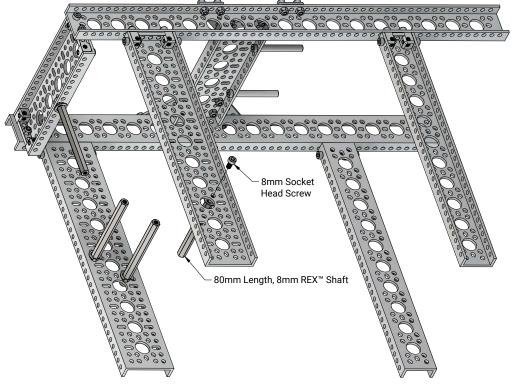




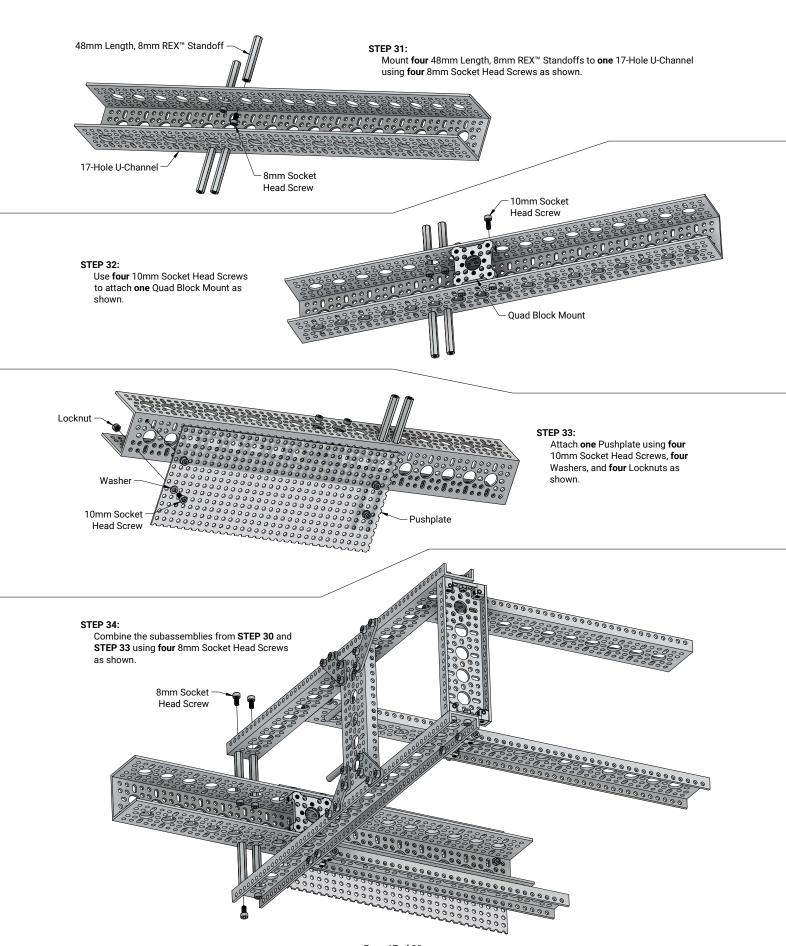








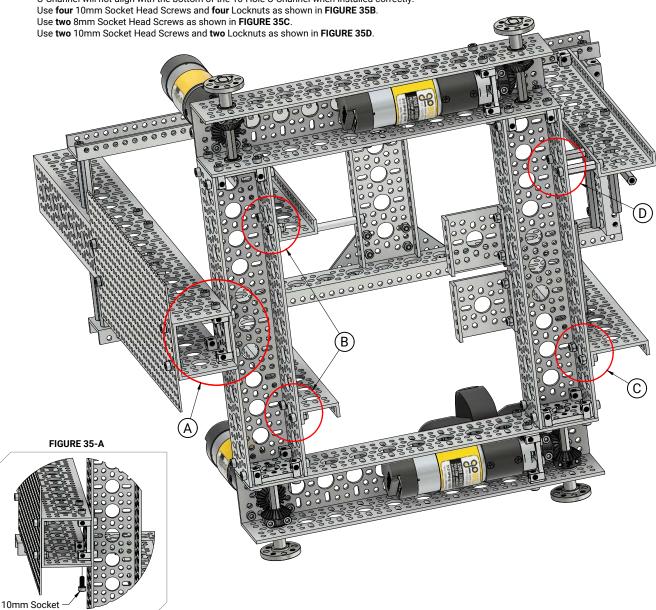
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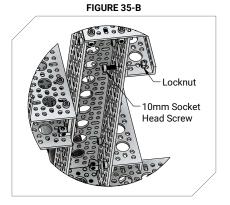


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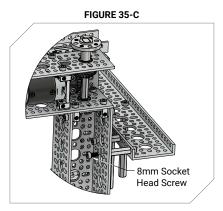
#### **STEP 35:**

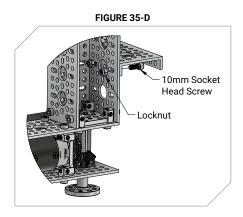
Combine the subassemblies from STEP 16 and STEP 34:
Use four 10mm Socket Head Screws as shown in FIGURE 35A. Note that the 17-Hole U-Channel will not align with the bottom of the 10-Hole U-Channel when installed correctly.





Head Screw



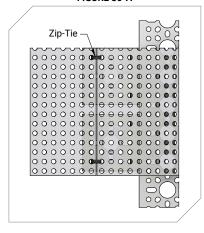


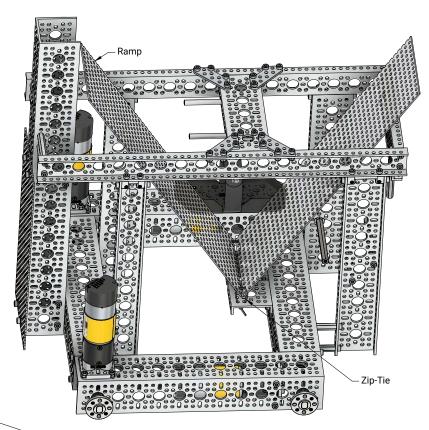
#### **STEP 36:**

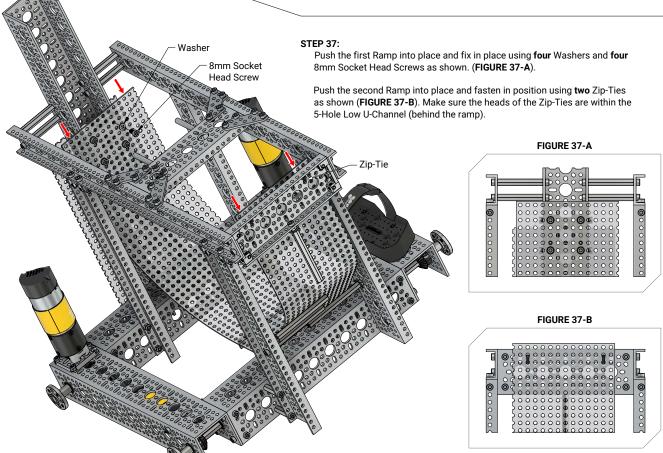
Use  $\boldsymbol{two}$  Zip-Ties to fasten  $\boldsymbol{two}$  Ramps in place as shown.

Make sure the "heads" of the Zip-Ties are below the 1-Hole Low U-Channel and that the Ramps both bend into position and lie flat against the 1-Hole Low U-Channels (FIGURE 36-A).

FIGURE 36-A



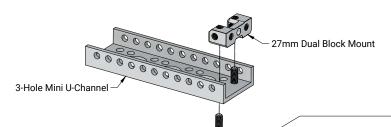




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Attach **one** 27mm Dual Block Mount to **one** 3-Hole Mini U-Channel as shown using **two** 12mm Socket Head Screws. Note the orientation of the 27mm Dual Block Mount.



#### STEP 39:

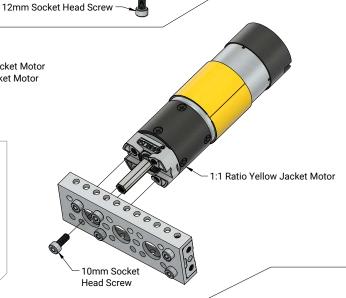
Convert **one** 19.2:1 Ratio Yellow Jacket Motor to a 1:1 Ratio Yellow Jacket Motor using **one** 1:1 Coupler (**FIGURE 39-A**). Attach the 1:1 Ratio Yellow Jacket Motor using **four** 10mm Socket Head Screws as shown.

#### FIGURE 39-A

Watch this video to see how to convert a 19.2:1 Ratio Yellow Jacket Motor to a 1:1 Ratio Yellow Jacket Motor: http://bit.ly/41fQtuj





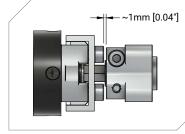


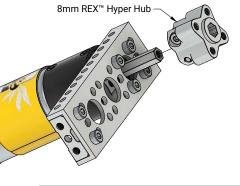
### **STEP 40:**

Attach **one** 8mm REX $^{\text{\tiny{M}}}$  Hyper Hub as shown.

A credit card is approximately 1mm thick and can be helpful in spacing the 8mm REX™ Hyper Hub away from the 10mm Socket Head Screws to achieve proper alignment.

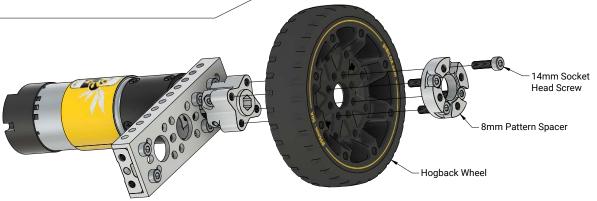
# FIGURE 40-A

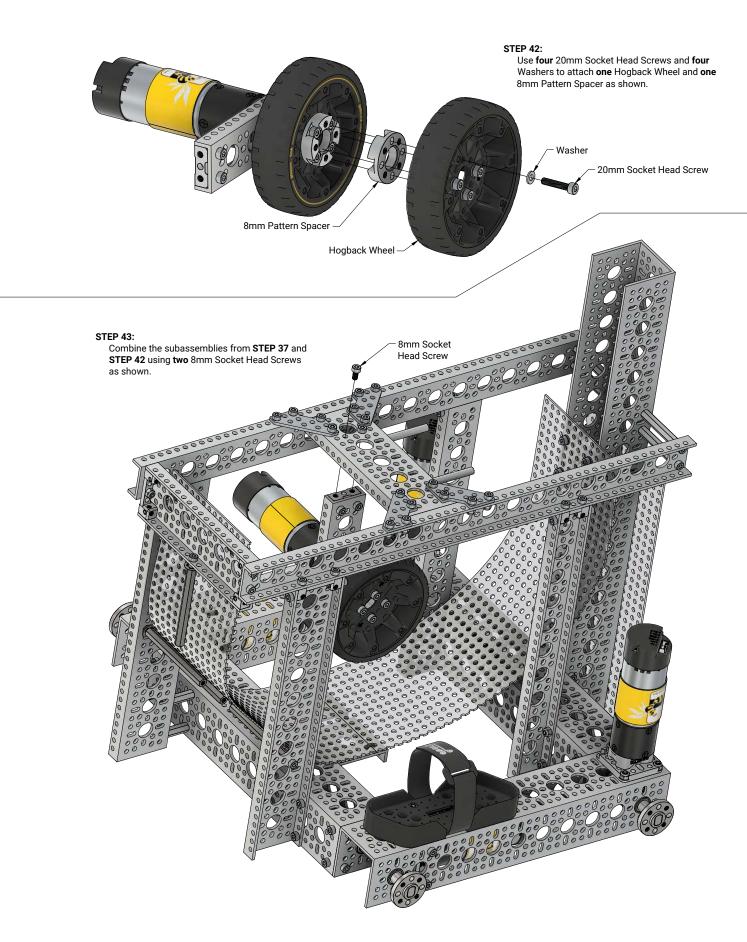




#### **STEP 41:**

Attach **one** Hogback Wheel and **one** 8mm Pattern Spacer using **four** 14mm Socket Head Screws as shown.

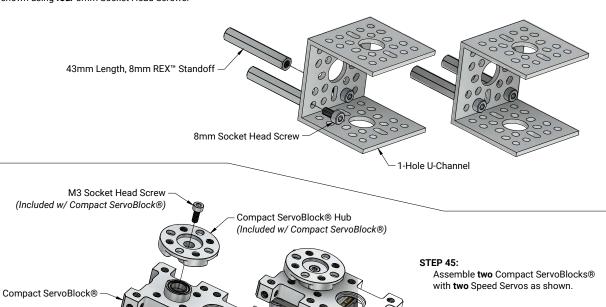




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#### **STEP 44:**

Assemble **two** 1-Hole U-Channels and **four** 43mm Length, 8mm REX™ Standoffs as shown using **four** 8mm Socket Head Screws.



Washer

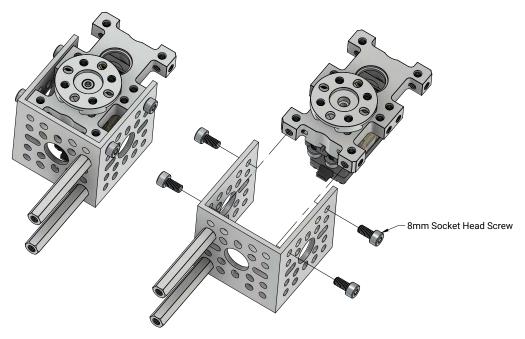
8mm Socket Head Screw (Included w/ Compact ServoBlock®)

Speed Servo

# STEP 46:

(Included w/ Compact ServoBlock®)

Combine the assembled ServoBlocks® with the 1-Hole U-Channels from **STEP 44** as shown using **eight** 8mm Socket Head Screws.

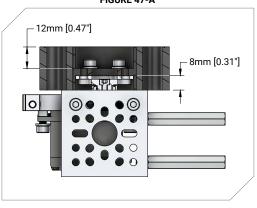




#### **STEP 47:**

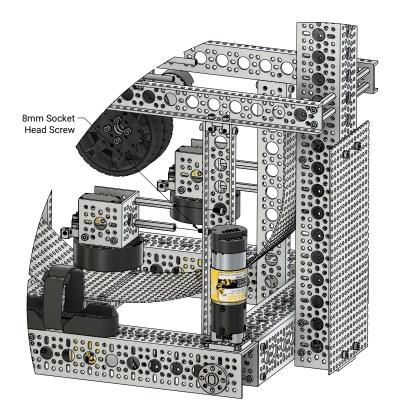
Attach **two** Gecko® Wheels with **eight** 8mm Socket Head Screws and **eight** Washers as shown.

FIGURE 47-A

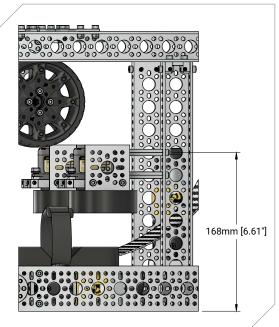


# **STEP 48:**

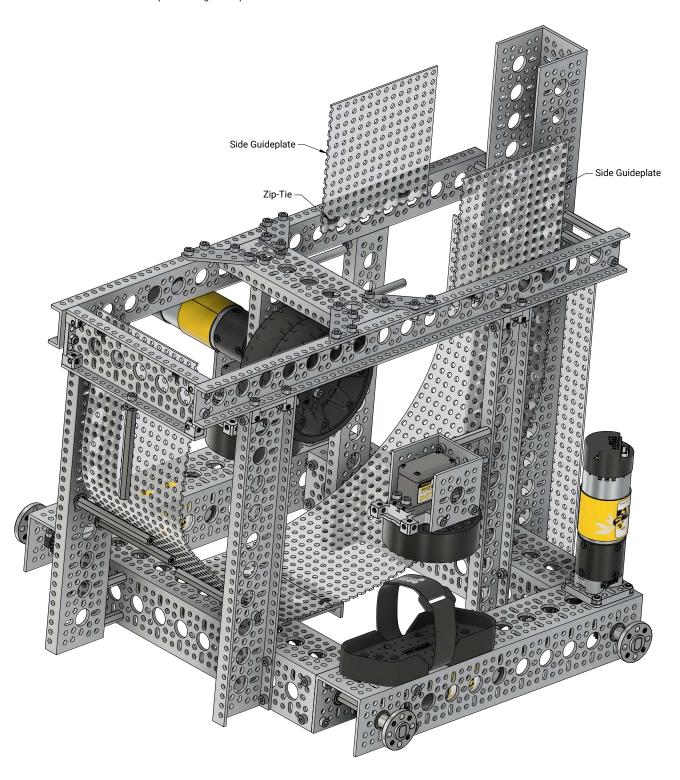
Attach the assemblies from STEP 43 and STEP 47 using four 8mm Socket Head Screws as shown. Note the locations (FIGURE 48-A).



# FIGURE 48-A



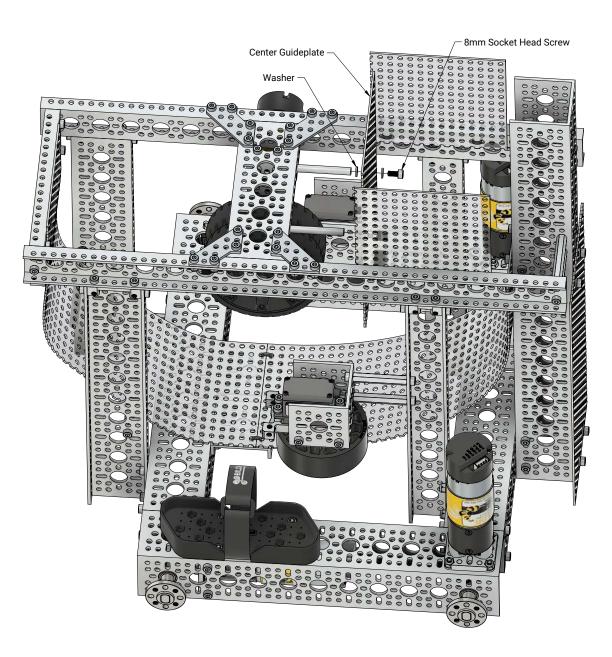
**STEP 49:**Fasten **two** Side Guideplates using **four** Zip-Ties as shown.



# FIGURE 50-A 100mm [3.94"]

# STEP 50:

Use **two** 8mm Socket Head Screws and **four** Washers to fasten **one** Center Guideplate as shown. The height should match the Side Guideplates (**FIGURE 50-A**).

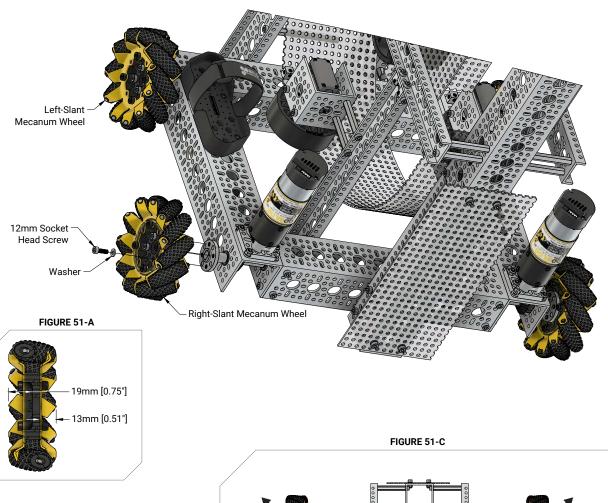


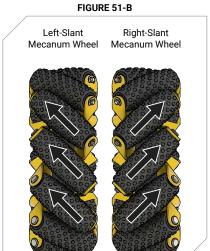
#### STEP 51:

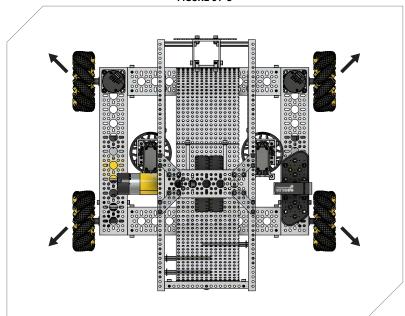
Attach **two** Right-Slant Mecanum Wheels and **two** Left-Slant Mecanum Wheels using **sixteen** Washers and **sixteen** 12mm Socket Head Screws as shown.

The Mecanum Wheels should mount to the Hub-Shafts from the "shallow" side of the Mecanum Wheels (FIGURE 51-A).

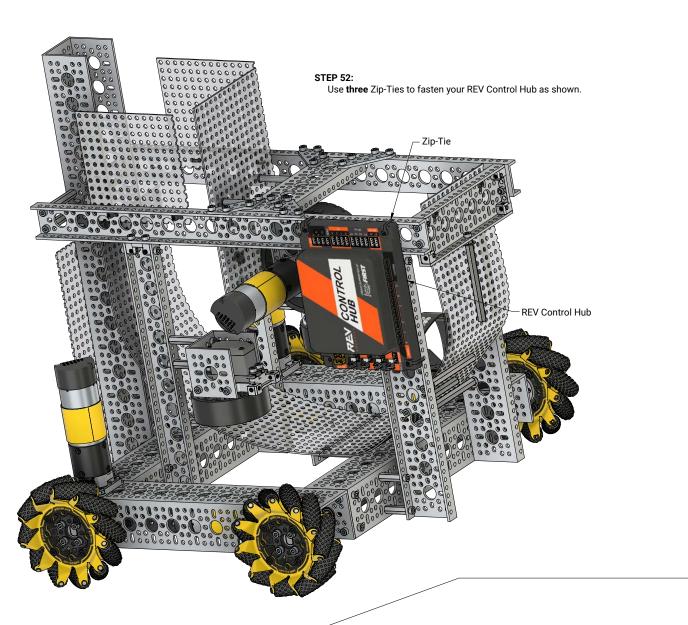
Note the configuration of the differently slanted wheels. In the correct configuration, the rollers on the wheels will point out diagonally from the center of the robot when viewed from above (FIGURE 51-C).



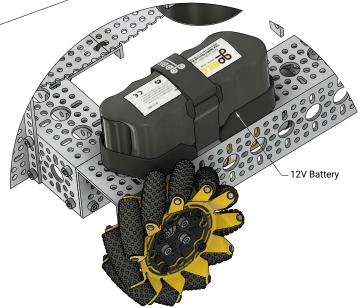




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STEP 53: Install one 12V Battery as shown.



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# **Great Job!**

You've completed the assembly! You're almost there—next up is wiring and programming your robot. Remember, this is just the beginning of what you can accomplish. Stay curious, and enjoy the journey ahead!

